Lecture 1: Introduction

André Martins



Deep Structured Learning Course, Fall 2019

Course Website

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https://andre-martins.github.io/pages/
deep-structured-learning-ist-fall-2019.html
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There I'll post:

Syllabus

• ...

- Lecture slides
- Literature pointers
- Homework assignments

Outline

1 Introduction

2 Class Administrativia

B Recap

- Linear Algebra
- Probability Theory
- Optimization

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What is "Deep Learning"?



- Neural networks?
- Neural networks with many hidden layers?
- Anything beyond shallow (linear) models for statistical learning?
- Anything that learns representations?
- A form of learning that is really intense and profound?

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Where is the "Structure"?



- In the input objects (text, graphs, images, ...)
- In the outputs we want to predict (parsing, graph labeling, image segmentation, ...)
- In our model (convolutional networks, attention mechanisms)
- Related: **latent structure** (typically a way of encoding prior knowledge into the model)

This Course: "Deep Learning + Structure"





Lots of recent breakthroughs:

- Object recognition
- Speech and language processing
- Chatbots and dialog systems
- Self-driving cars
- Machine translation
- Solving games (Atari, Go)

No signs of slowing down...



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Microsoft's Deep Learning Project Outperforms Humans In Image Recognition



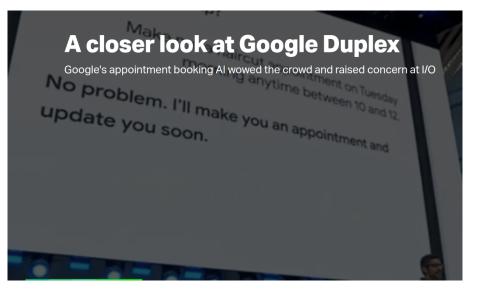
Michael Thomsen, CONTRIBUTOR I write about tech, video games, science and culture. FULL BIO ~ Opinions expressed by Forbes Contributors are their own.



Microsoft's new breakthrough: AI that's as good as humans at listening... on the phone

Microsoft's new speech-recognition record means professional transcribers could be among the first to lose their jobs to artificial intelligence.

By Liam Tung | October 19, 2016 -- 10:10 GMT (11:10 BST) | Topic: Innovation



Who is wearing glasses? man woman





Is the umbrella upside down?



Where is the child sitting? fridge arms





How many children are in the bed? 2 1





IST, Fall 2019 11 / 82

The Great A.I. Awakening

How Google used artificial intelligence to transform Google Translate, one of its more popular services — and how machine learning is poised to reinvent computing itself.

BY GIDEON LEWIS-KRAUS DEC. 14, 2016

Google unleashes deep learning tech on language with Neural Machine Translation

Posted Sep 27, 2016 by Devin Coldewey, Contributor







IST, Fall 2019 12 / 82

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Siri and Alexa Are Fighting to Be Your Hotel Butler

By Hui-yong Yu and Spencer Soper

March 22, 2017, 9:00 AM GMT Updated on March 22, 2017, 2:13 PM GMT

- → Hotels are new frontier for voice-command technologies
- → Wynn Las Vegas was first to install Alexa devices in December





AlphaGo Beats Go Human Champ: Godfather Of Deep Learning Tells Us Do Not Be Afraid Of Al

21 March 2016, 10:16 am EDT By Aaron Mamiit Tech Times



Last week, Google's artificial intelligence program

Last week, Google's artificial intelligence program AlphaGo dominated its match with South Korean world Go champion Lee Sedol, winning with a 4-1 score.

The achievement stunned artificial intelligence experts, who previously thought that Google's computer program would need at least 10 more years before developing enough to be able to beat a human world champion.

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Why Now?

Why does deep learning work now, but not 20 years ago?

Many of the core ideas were there, after all.

But now we have:

- more data
- more computing power
- better software engineering
- a few algorithmic innovations (many layers, ReLUs, better initialization and learning rates, dropout, LSTMs, convolutional nets)

Why does gradient-based optimization work at all in neural nets despite the non-convexity?

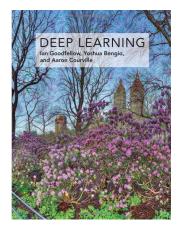
One possible, partial answer:

- there are generally many hidden units
- there are many ways a neural net can approximately implement the desired input-output relationship
- we only need to find one

Recommended Books

Main book:

• Deep Learning. Ian Goodfellow, Yoshua Bengio, and Aaron Courville. MIT Press, 2016. Chapters available at http://deeplearningbook.org



Secondary books:

- Machine Learning: a Probabilistic Perspective. Kevin P. Murphy. MIT Press, 2013.
- Linguistic Structured Prediction. Noah A. Smith. Morgan & Claypool Synthesis Lectures on Human Language Technologies. 2011.

Tentative Syllabus

Sep 16-20	Introduction and Course Description
Sep 23–27	Linear Classifiers
Sep 30–Oct 4	Feedforward Neural Networks
Oct 7–11	Training Neural Networks
Oct 14–18	Linear Sequence Models
Oct 21–25	Representation Learning and Convolutional Networks
Oct 28–Nov 1	Structured Prediction and Graphical Models
Nov 4–8	Recurrent Neural Networks
Nov 11–15	Sequence-to-Sequence Learning
Nov 18–22	Attention Mechanisms and Neural Memories
Nov 25–29	Deep Reinforcement Learning
Dec 2–6	Deep Generative Models (VAEs, GANs)
Dec 9–13	Final Projects I
Dec 16–20	Final Projects II

Image: A matrix and a matrix

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What This Class Is About

- Introduction to deep learning
- Introduction to structured prediction
- Goal: after finishing this class, you should be able to:
 - Understand how deep learning works without magic
 - Understand the intuition behind deep structured learning models
 - Apply the learned techniques on a practical problem (NLP, vision, ...)

• Target audience:

 MSc/PhD students with basic background in ML and good programming skills

It's **not** about:

. . .

- Just playing with a deep learning toolkit without learning the fundamental concepts
- Introduction to ML (see Mário Figueiredo's Statistical Learning course and Jorge Marques' Estimation and Classification course)
- Optimization (check João Xavier's Non-Linear Optimization course)
- Natural Language Processing

Prerequisites

- Calculus and basic linear algebra
- Basic probability theory
- Basic knowledge of machine learning
- Programming (Python & PyTorch preferred)
- Helpful: basic optimization

Course Information

- Instructors: André Martins & Vlad Niculae
- TAs: Gonçalo Correia & Ben Peters
- Location: LT2 (North Tower, 4th floor)
- Schedule: Mondays/Fridays 10:00–11:30 (tentative)
- Communication:

piazza.com/tecnico.ulisboa.pt/fall2019/pdeecdsl



IST, Fall 2019 24 / 82

Grading

- 4 homework assignments: 60%
 - Theoretical questions & implementation
 - Late days: 10% penalization each late day
- Final project (in groups of 2–3): 40%
 - Final class presentations & poster session (tentative)

Final Project

- **Possible idea:** apply a deep learning technique to a structured problem relevant to your research (NLP, vision, robotics, ...)
- Otherwise, pick a project from a list of suggestions
- Must be finished this semester
- Four evaluation stages: project proposal (10%), midterm report (10%), final report (10%, conference paper format), class presentation (10%)
- List of project suggestions will be made available soon

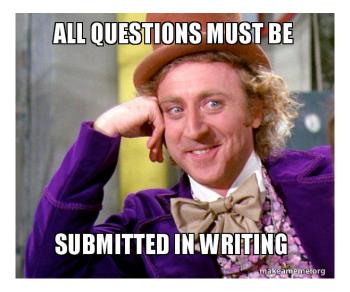
Collaboration Policy

- Assignments are individual
- Students may discuss the questions, as long as they write their own answers and their own code
- If this happens, acknowledge with whom you collaborate!
- Zero tolerance on plagiarism!!
- Always credit your sources!!!

Caveat

- This is the second year I'm teaching this class
- ... which means you're the second batch of students taking it :)
- Constructive feedback will be highly appreciated (and encouraged!)

Questions?



André Martins (IST)

IST, Fall 2019 29 / 82

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Quick Background Recap

Slide credits: Prof. Mário Figueiredo (taken from his LxMLS class)



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Linear Algebra

• Linear algebra provides (among many other things) a compact way of representing, studying, and solving linear systems of equations

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- Example: the system

$$4 x_1 - 5 x_2 = -13$$

-2 x₁ + 3 x₂ = 9

can be written compactly as Ax = b, where

$$A = \left[\begin{array}{cc} 4 & -5 \\ -2 & 3 \end{array} \right], \ b = \left[\begin{array}{c} -13 \\ 9 \end{array} \right],$$

and can be solved as

$$x = A^{-1}b = \begin{bmatrix} 1.5 & 2.5 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} -13 \\ 9 \end{bmatrix} = \begin{bmatrix} 3 \\ 5 \end{bmatrix}.$$

Notation: Matrices and Vectors

• $A \in \mathbb{R}^{m \times n}$ is a matrix with *m* rows and *n* columns.

$$A = \left[\begin{array}{cccc} A_{1,1} & \cdots & A_{1,n} \\ \vdots & \ddots & \vdots \\ A_{m,1} & \cdots & A_{m,n} \end{array} \right].$$

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- A matrix with 1 row and *n* columns is called a row vector.

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• Outer product between vectors $x \in \mathbb{R}^n$ and $y \in \mathbb{R}^m$: $x y^T \in \mathbb{R}^{n \times m}$, where $(x y^T)_{i,j} = x_i y_j$.

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IST, Fall 2019 36 / 82

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- Transpose of sum: $(A + B)^T = A^T + B^T$.

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$$\|x\|_2 = \sqrt{\langle x, x \rangle} = \sqrt{x^T x} = \sqrt{\sum_{i=1}^n x_i^2}.$$

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• Notable case: the ℓ_0 "norm" (not): $||x||_0 = |\{i : x_i \neq 0\}|$.

Special Matrices

• The identity matrix $I \in \mathbb{R}^{n \times n}$ is a square matrix such that

$$I_{ij} = \begin{cases} 1 & i = j \\ 0 & i \neq j \end{cases} \quad I = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix}$$

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IST, Fall 2019 38 / 82

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- Lower triangular matrix: $(j > i) \Rightarrow A_{i,j} = 0.$

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Matrix Inverse

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- There are many algorithms to compute A^{-1} ; general case, computational cost $O(n^3)$.

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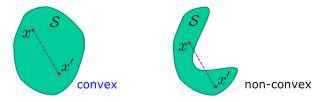
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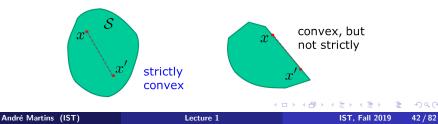
Convex Sets

Convex and strictly convex sets

 $\mathcal{S} \text{ is convex if } x, x' \in \mathcal{S} \ \Rightarrow \forall \lambda \in [0,1], \ \lambda x + (1-\lambda) x' \in \mathcal{S}$



 \mathcal{S} is strictly convex if $x, x' \in \mathcal{S} \Rightarrow \forall \lambda \in (0, 1), \ \lambda x + (1 - \lambda)x' \in \operatorname{int}(\mathcal{S})$



Convex Functions

Convex and strictly convex functions

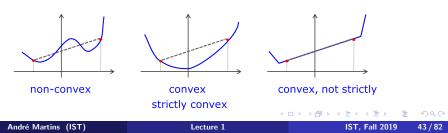
Extended real valued function: $f: \mathbb{R}^N \to \overline{\mathbb{R}} = \mathbb{R} \cup \{+\infty\}$

Domain of a function: $\operatorname{dom}(f) = \{x : f(x) \neq +\infty\}$

f is a convex function if

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Outline

1 Introduction

2 Class Administrativia

8 Recap

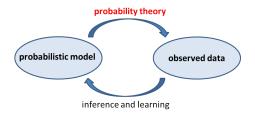
Linear Algebra

Probability Theory

Optimization

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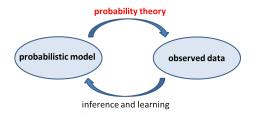
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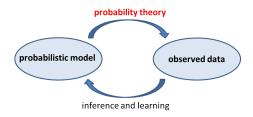
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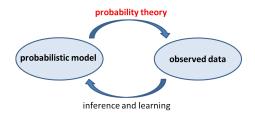
• "Essentially, all models are wrong, but some are useful"; G. Box, 1987

IST, Fall 2019 45 / 82

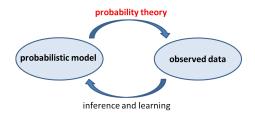
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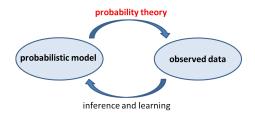
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- Natural tool to model uncertainty, information, knowledge, belief, ...
- ...thus also learning, decision making, inference, ...

What is probability?

• Classical definition:
$$\mathbb{P}(A) = \frac{N_A}{N}$$

...with N mutually exclusive equally likely outcomes, N_A of which result in the occurrence of event A. Laplace, 1814

Example: $\mathbb{P}(\text{randomly drawn card is }) = 13/52.$

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• Subjective probability: $\mathbb{P}(A)$ is a degree of belief. *de Finetti, 1930s*

...gives meaning to $\mathbb{P}($ "Tomorrow it will rain").

Key concepts: Sample space and events

- Sample space $\mathcal{X} =$ set of possible outcomes of a random experiment. Examples:
 - Tossing two coins: $\mathcal{X} = \{HH, TH, HT, TT\}$
 - Roulette: $\mathfrak{X} = \{1, 2, ..., 36\}$
 - Draw a card from a shuffled deck: $\mathfrak{X} = \{A, 2, 2, ..., Q \diamondsuit, K \diamondsuit\}$.

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- An event A is a subset of \mathfrak{X} : $A \subseteq \mathfrak{X}$.

Examples:

- "exactly one H in 2-coin toss": $A = \{TH, HT\} \subset \{HH, TH, HT, TT\}$.
- "odd number in the roulette": $B = \{1, 3, ..., 35\} \subset \{1, 2, ..., 36\}$.
- "drawn a \heartsuit card": $C = \{A\heartsuit, 2\heartsuit, ..., K\heartsuit\} \subset \{A\clubsuit, ..., K\diamondsuit\}$

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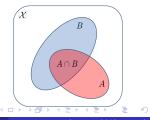
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- Probability is a function that maps events A into the interval [0, 1].
 Kolmogorov's axioms (1933) for probability P
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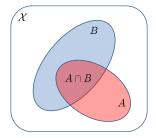
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- From these axioms, many results can be derived. Examples:
- $\mathbb{P}(\emptyset) = 0$
- $C \subset D \Rightarrow \mathbb{P}(C) \leq \mathbb{P}(D)$
- $\mathbb{P}(A \cup B) = \mathbb{P}(A) + \mathbb{P}(B) \mathbb{P}(A \cap B)$
- $\mathbb{P}(A \cup B) \leq \mathbb{P}(A) + \mathbb{P}(B)$ (union bound)



• If
$$\mathbb{P}(B) > 0$$
, $\mathbb{P}(A|B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)}$ (conditional prob. of A given B)

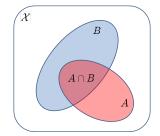
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• Example: $\mathfrak{X} = \text{``52 cards''}, A = \{3\heartsuit, 3\clubsuit, 3\diamondsuit, 3\clubsuit\}, \text{ and}$ $B = \{A\heartsuit, 2\heartsuit, ..., K\heartsuit\}; \text{ then, } \mathbb{P}(A) = 1/13, \mathbb{P}(B) = 1/4$ $\mathbb{P}(A \cap B) = \mathbb{P}(\{3\heartsuit\}) = \frac{1}{52}$

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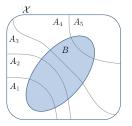
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Bayes Theorem

• Law of total probability: if $A_1, ..., A_n$ are a partition of \mathcal{X}

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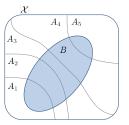


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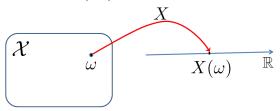
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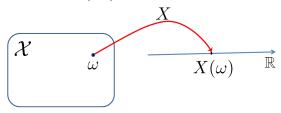
• Bayes' theorem: if $\{A_1, ..., A_n\}$ is a partition of \mathfrak{X}

$$\mathbb{P}(A_i|B) = \frac{\mathbb{P}(B \cap A_i)}{\mathbb{P}(B)} = \frac{\mathbb{P}(B|A_i) \mathbb{P}(A_i)}{\sum_j \mathbb{P}(B|A_j) \mathbb{P}(A_j)}$$

• A (real) random variable (RV) is a function: $X : \mathcal{X} \to \mathbb{R}$

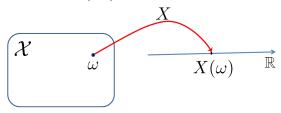


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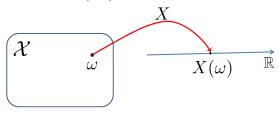
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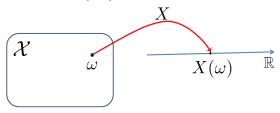
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$$\mathcal{X} = \{HH, HT, TH, TT\},\$$

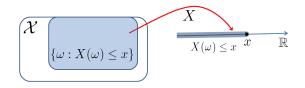
 $X(HH) = 2, X(HT) = X(TH) = 1, X(TT) = 0.$
Range of $X = \{0, 1, 2\}.$

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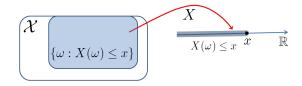


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- Example: number of head in tossing two coins, $\mathcal{X} = \{HH, HT, TH, TT\},$ X(HH) = 2, X(HT) = X(TH) = 1, X(TT) = 0.Range of $X = \{0, 1, 2\}.$
- Example: distance traveled by a tossed coin; range of $X = \mathbb{R}_+$.

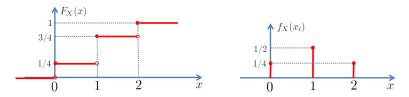
• Distribution function: $F_X(x) = \mathbb{P}(\{\omega \in \mathfrak{X} : X(\omega) \le x\})$



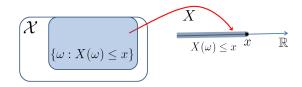
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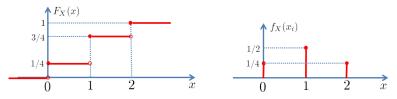
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• Probability mass function (discrete RV): $f_X(x) = \mathbb{P}(X = x)$,

$$F_X(x) = \sum_{\substack{x \in \mathcal{F}_X \\ x \in \mathcal{F}_X \\ x$$

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- Uniform: $X \in \{x_1, ..., x_K\}$, pmf $f_X(x_i) = 1/K$.
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Can be written compactly as $f_X(x) = p^x(1-p)^{1-x}$.

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• Binomial RV: $X \in \{0, 1, ..., n\}$ (sum on *n* Bernoulli RVs)

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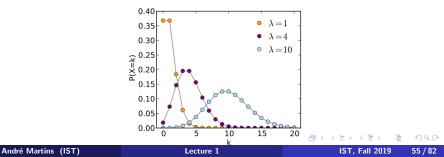
Binomial coefficients ("*n* choose x"): $\binom{n}{x} = \frac{n!}{(n-x)!x!}$ André Martins (IST) Lecture 1 Lecture

• Geometric(p): $X \in \mathbb{N}$, pmf $f_X(x) = p(1-p)^{x-1}$. (*e.g.*, number of trials until the first success).

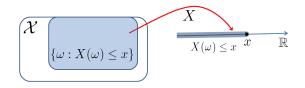
- Geometric(p): $X \in \mathbb{N}$, pmf $f_X(x) = p(1-p)^{x-1}$. (*e.g.*, number of trials until the first success).
- Poisson(λ): $X \in \mathbb{N} \cup \{0\}$, pmf $f_X(x) = \frac{e^{-\lambda}\lambda^x}{x!}$

Notice that $\sum_{x=0}^{\infty} \frac{\lambda^x}{x!} = e^{\lambda}$, thus $\sum_{x=0}^{\infty} f_X(x) = 1$.

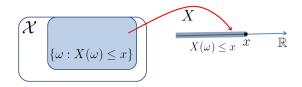
"...probability of the number of independent occurrences in a fixed (time/space) interval if these occurrences have known average rate"



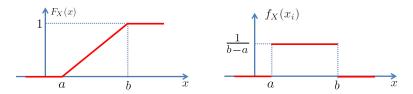
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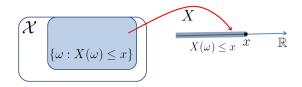
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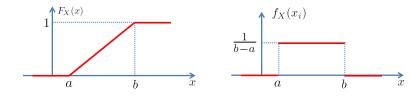
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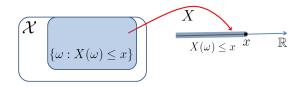


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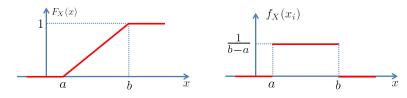


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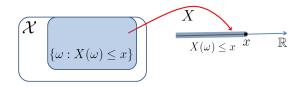


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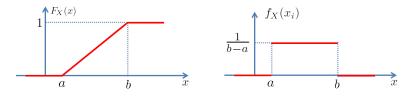
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IST, Fall 2019 56 / 82

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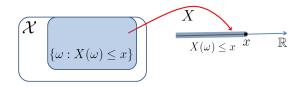
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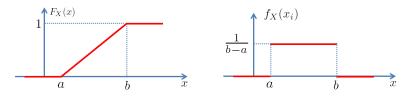
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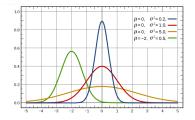
Important Continuous Random Variables

• Uniform: $f_X(x) = \text{Uniform}(x; a, b) = \begin{cases} \frac{1}{b-a} & \Leftarrow & x \in [a, b] \\ 0 & \Leftarrow & x \notin [a, b] \end{cases}$ (previous slide).

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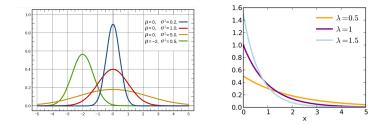
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• Expectation:
$$\mathbb{E}(X) = \begin{cases} \sum_{i} x_i f_X(x_i) & X \in \{x_1, ..., x_K\} \subset \mathbb{R} \\ \int_{-\infty}^{\infty} x f_X(x) dx & X \text{ continuous} \end{cases}$$

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Image: A matrix and a matrix

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- Linearity of expectation: $\mathbb{E}(X + Y) = \mathbb{E}(X) + \mathbb{E}(Y); \quad \mathbb{E}(\alpha X) = \alpha \mathbb{E}(X), \quad \alpha \in \mathbb{R}$

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$$\mathbb{E}(g(X)) = \begin{cases} \sum_{i} g(x_i) f_X(x_i) & X \text{ discrete, } g(x_i) \in \mathbb{R} \\ \int_{-\infty}^{\infty} g(x) f_X(x) dx & X \text{ continuous} \end{cases}$$

IST, Fall 2019 59 / 82

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• Probability as expectation of indicator, $\mathbf{1}_A(x) = \begin{cases} 1 & \Leftarrow & x \in A \\ 0 & \Leftarrow & x \notin A \end{cases}$

$$\mathbb{P}(X \in A) = \int_A f_X(x) \, dx = \int \mathbf{1}_A(x) \, f_X(x) \, dx = \mathbb{E}(\mathbf{1}_A(X))$$

• Joint pmf of two discrete RVs: $f_{X,Y}(x,y) = \mathbb{P}(X = x \land Y = y).$

Extends trivially to more than two RVs.

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• Conditional pmf (discrete RVs):

$$f_{X|Y}(x|y) = \mathbb{P}(X = x|Y = y) = \frac{\mathbb{P}(X = x \land Y = y)}{\mathbb{P}(Y = y)} = \frac{f_{X,Y}(x,y)}{f_Y(y)}$$

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Also valid in the mixed case (e.g., X continuous, Y discrete).

Joint, Marginal, and Conditional Probabilities: An Example

• A pair of binary variables $X, Y \in \{0, 1\}$, with joint pmf:

$f_{X,Y}(x,y)$	Y = 0	Y = 1	
X = 0	1/5	2/5	
X = 1	1/10	3/10	

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• Marginals: $f_X(0) = \frac{1}{5} + \frac{2}{5} = \frac{3}{5}$, $f_X(1) = \frac{1}{10} + \frac{3}{10} = \frac{4}{10}$, $f_Y(0) = \frac{1}{5} + \frac{1}{10} = \frac{3}{10}$, $f_Y(1) = \frac{2}{5} + \frac{3}{10} = \frac{7}{10}$.

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• Conditional probabilities:

$f_{X Y}(x y)$	Y = 0	Y = I	$f_{Y X}(y x)$	Y = 0	Y = 1
X = 0	2/3	4/7	X = 0	1/3	2/3
X = I	1/3	3/7	X = 1	1/4	3/4

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An Important Multivariate RV: Multinomial

• Multinomial: $X = (X_1, ..., X_K)$, $X_i \in \{0, ..., n\}$, such that $\sum_i X_i = n$,

$$f_X(x_1,...,x_K) = \begin{cases} \binom{n}{x_1 x_2 \cdots x_K} p_1^{x_1} p_2^{x_2} \cdots p_k^{x_K} & \Leftarrow \sum_i x_i = n \\ 0 & \Leftarrow \sum_i x_i \neq n \end{cases}$$

$$\binom{n}{x_1 \ x_2 \ \cdots \ x_K} = \frac{n!}{x_1! \ x_2! \ \cdots \ x_K!}$$

Parameters: $p_1, ..., p_K \ge 0$, such that $\sum_i p_i = 1$.

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- Generalizes the binomial from binary to K-classes.
- Example: tossing *n* independent fair dice, $p_1 = \cdots = p_6 = 1/6$. $x_i =$ number of outcomes with *i* dots. Of course, $\sum_i x_i = n$.

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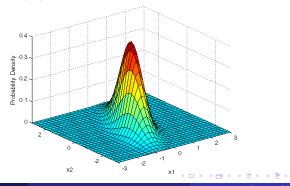
• Parameters: vector $\mu \in \mathbb{R}^n$ and matrix $C \in \mathbb{R}^{n \times n}$. Expected value: $\mathbb{E}(X) = \mu$. Meaning of C: next slide.

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Parameters: vector μ ∈ ℝⁿ and matrix C ∈ ℝ^{n×n}.
 Expected value: 𝔼(X) = μ. Meaning of C: next slide.



$$\operatorname{cov}(X,Y) = \mathbb{E}\Big[(X - \mathbb{E}(X)) (Y - \mathbb{E}(Y)) \Big] = \mathbb{E}(X Y) - \mathbb{E}(X) \mathbb{E}(Y)$$

• Covariance between two RVs:

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• Covariance matrix of multivariate RV, $X \in \mathbb{R}^{n}$: $\operatorname{cov}(X) = \mathbb{E}\Big[(X - \mathbb{E}(X)) (X - \mathbb{E}(X))^{T} \Big] = \mathbb{E}(X X^{T}) - \mathbb{E}(X) \mathbb{E}(X)^{T}$

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- Covariance of Gaussian RV, $f_X(x) = \mathcal{N}(x; \mu, C) \Rightarrow \operatorname{cov}(X) = C$

Let $A \in \mathbb{R}^{n \times n}$ be a matrix and $a \in \mathbb{R}^n$ a vector.

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 and $Y = C^{-1/2}(X - \mu)$, then $f_Y(y) = \mathcal{N}(y; 0, I)$.

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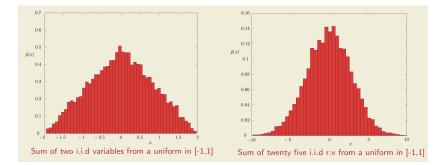
$$\mathbb{E}[Y_n] = \sum_{i=1}^n \mu_i \equiv \mu \qquad \text{var}(Y_n) = \sum_i \sigma_i^2 \equiv \sigma$$
• ...thus, if $Z_n = \frac{Y_n - \mu}{\sigma}$
 $\mathbb{E}[Z_n] = 0 \qquad \text{var}(Z_n) = 1$

• Central limit theorem (CLT): under some mild conditions on X₁,..., X_n

$$\lim_{n\to\infty} Z_n \sim \mathcal{N}(0,1)$$

Central Limit Theorem

Illustration



Important Inequalities

• Markov's ineqality: if $X \ge 0$ is an RV with expectation $\mathbb{E}(X)$, then

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• Chebyshev's inequality: $\mu = \mathbb{E}(Y)$ and $\sigma^2 = \operatorname{var}(Y)$, then

$$\mathbb{P}(|Y-\mu| \ge s) \le rac{\sigma^2}{s^2}$$

...simple corollary of Markov's inequality, with $X = |Y - \mu|^2$, $t = s^2$

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Implication for correlation:

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Other Important Inequalities: Jensen

• Recall that a real function g is convex if, for any x, y, and $\alpha \in [0, 1]$

$$g(\alpha x + (1 - \alpha)y) \le \alpha g(x) + (1 - \alpha)g(y)$$

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Examples: $\mathbb{E}(X)^2 \leq \mathbb{E}(X^2) \Rightarrow \operatorname{var}(X) = \mathbb{E}(X^2) - \mathbb{E}(X)^2 \geq 0.$

 $\mathbb{E}(\log X) \leq \log \mathbb{E}(X)$, for X a positive RV.

Entropy of a discrete RV
$$X \in \{1, ..., K\}$$
: $H(X) = -\sum_{x=1}^{K} f_X(x) \log f_X(x)$

IST, Fall 2019 72 / 82

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• h(X) can be positive or negative. Example, if $f_X(x) = \text{Uniform}(x; a, b), \ h(X) = \log(b - a).$

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Kullback-Leibler divergence (KLD) between two pmf:

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$$\begin{array}{ll} \text{Positivity:} & D(f_X \| g_X) \geq 0 \\ & D(f_X \| g_X) = 0 \ \Leftrightarrow \ f_X(x) = g_X(x), \text{ almost everywhere} \end{array}$$

Mutual information (MI) between two random variables:

$$I(X;Y) = D(f_{X,Y}||f_X f_Y)$$

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MI is a measure of dependency between two random variables

Recommended Reading

- K. Murphy, "Machine Learning: A Probabilistic Perspective", MIT Press, 2012.
- L. Wasserman, "All of Statistics: A Concise Course in Statistical Inference", Springer, 2004.

Outline

1 Introduction

2 Class Administrativia

8 Recap

Linear Algebra

Probability Theory

Optimization

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Minimizing a function

- We are given a function $f : \mathbb{R}^n \to \mathbb{R}$.
- Goal: find x^* that minimizes $f : \mathbb{R}^n \to \mathbb{R}$.
- Global minimum: for any $x \in \mathbb{R}^n$, $f(x^*) \leq f(x)$.
- Local minimum: for any $||x x^*|| \le \delta \Rightarrow f(x^*) \le f(x)$.

Are these global minima ?

• No, (local minima, saddle points, ...)

Iterative descent methods

Goal: find the minimum/minimizer of $f : \mathbb{R}^d \to \mathbb{R}$

- Proceed in small steps in the optimal direction till a stopping criterion is met.
- Gradient descent: updates of the form: $x^{(t+1)} \leftarrow x^{(t)} \eta_{(t)} \nabla f(x^{(t)})$

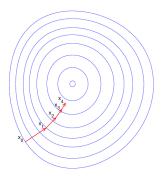


Figure: Illustration of gradient descent. The blue circles correspond to the function values at different points, while the red lines correspond to the André Martins (IST) TST, Fall 2019 78/82

Convex functions

Pro: Guarantee of a global minima \checkmark

(y, f(y))(x, f(x))

Figure: Illustration of a convex function. The line segment between any two points on the graph lies entirely above the curve.

Non-Convex functions

Pro: No guarantee of a global minima \boldsymbol{X}

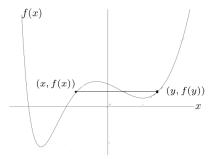


Figure: Illustration of a non-convex function. Note the line segment intersecting the curve.

André	Martins	(IST)	

Thank you!

Questions?



IST, Fall 2019 81 / 82

References I

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IST, Fall 2019 82 / 82

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